

17516-1320

**Amendment to the Claims:**

This listing of the claims will replace all prior versions, and listings, of claims in the application.

**Listing of the Claims:**

Please cancel claims 1-5, 7-15 and 17.

16. (Currently amended) The system of claim 9 A robotic surgical system comprising:

a manipulator movably supporting at least one surgical instrument;

a controller comprising an input device, the controller operatively associated with the manipulator to cause selective movement of the instrument in response to inputs from an operator at the controller; and

a clutching assembly that is movable from a first mode to a second mode,

wherein the clutch assembly in the first mode is configured to interrupt the operative association between the controller and the manipulator so that the one of the input device and the surgical instrument is moved from one position to another while the other of the input device and surgical instrument is held in a substantially fixed position and to inhibit independent repositioning of the input device in at least one rotational degree of freedom, and the clutching assembly in the second mode is configured to reestablish the operative association between the manipulator and the controller after the surgical instrument or input device has been repositioned.